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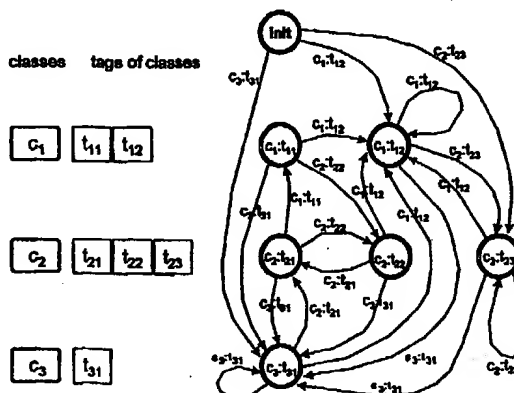
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(54) Title: FSTs APPROXIMATING HIDDEN MARKOV MODELS AND TEXT TAGGING USING SAME



(57) Abstract

A sequential transducer, derived from a Hidden Markov Model, that closely approximates the behavior of the stochastic model. The invention provides (a) a method (called n-type approximation) of deriving a simple finite-state transducer which is applicable in all cases, from HMM probability matrices, (b) a method (called s-type approximation) for building a precise HMM transducer for selected cases which are taken from a training corpus, (c) a method for completing the precise (s-type) transducer with sequences from the simple (n-type) transducer, which makes the precise transducer applicable in all cases, and (d) a method (called b-type approximation) for building an HMM transducer with variable precision which is applicable in all cases. This transformation is especially advantageous for part-of-speech tagging because the resulting transducer can be composed with other transducers that encode correction rules for the most frequent tagging errors. The speed of tagging is also improved. The described methods have been implemented and successfully tested on six languages.

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**FSTs approximating Hidden Markov Models and text tagging using same**

The present invention relates to computer-based text processing, and more particularly to techniques for part-of-speech tagging by finite state transducer (FST) derived from a Hidden Markov Model (HMM).

Part-of-speech tagging of machine-readable text, whereby tags are applied to words in a sentence so as to identify a word's part-of-speech (e.g. noun-singular, verb-present-1st person plural), are known. Such tags are typically of a standardised form, such as specified under the Text Encoding Initiative (TEI). A text or corpus, once tagged, finds use, for example, in information retrieval from the text and statistical analysis of the text.

Probabilistic HMM based taggers are known from Bahl and Mercer (1976) and Church (1988); see Section H: References at the end of this disclosure. They select among the part-of-speech tags that are found for a word in the dictionary, the most probable tag based on the word's context, i.e. based on the adjacent words.

However, a problem with a conventional HMM based tagger is that it cannot be integrated with other finite state tools which perform other steps of text analysis/manipulation.

One method is to generate an FST performing part-of-speech tagging from a set of rules written by linguists (Chanod and Tapanainen, 1995). This, however, takes considerable time and produces very large automata (or sets of automata that cannot be integrated with each other for reasons of size) which perform the tagging relatively slowly. Such an FST may also be non-deterministic, i.e. for an input sentence it may provide more than one solution or no solutions at all.

The present invention provides methods to approximate a Hidden Markov Model (HMM) used for part-of-speech tagging, by a finite-state transducer. (An identical model of an HMM by a transducer (without weights) is in many cases impossible.) In specific embodiments there are provided (a) a method (called n-type approximation) of deriving a simple finite-state transducer which is applicable in all cases, from HMM probability matrices, (b) a method (called s-type approximation) for building a precise HMM transducer for selected cases which are taken from a training corpus, (c) a method for completing the precise (s-type) transducer with sequences from the simple (n-type) transducer, which makes the precise transducer applicable in all cases, and (d) a method (called b-type approximation) for building an HMM transducer with variable precision which is applicable in all cases.

The invention provides a method of generating a text tagging FST according to any of claims 1, 5 and 9 of the appended claims, or according to any of the particular embodiments described herein.

The invention further provides a method of generating a composite finite state transducer by composing the HMM-derived FST with one or more further text-manipulating FSTs.

The invention further provides a method of tagging a text using the aforementioned HMM-derived FST or the composite FST.

The invention further provides a text processing system according to claim 11 of the appended claims, and a recordable medium according to claim 12 of the appended claims.

The HMM transducer builds on the data (probability matrices) of the underlying HMM. The accuracy of the data collected in the HMM training process has an impact on the tagging accuracy of both the HMM itself and the derived transducer. The training of this HMM can be done on either a tagged or untagged corpus, and is not discussed in detail herein since it is exhaustively described in the literature (Bahl and Mercer, 1976; Church, 1988).

An advantage of Finite-State taggers according to the invention is that tagging speed when using transducers is up to five times higher than when using the underlying HMM (cf. section F hereinbelow).

However, a main advantage of the invention is that integration with tools performing further steps of text analysis is possible: transforming an HMM into a FST means that this transducer can be handled by the finite state calculus and therefore directly integrated into other finite-state text processing tools, such as those available from XEROX Corp., and elsewhere. Since the tagger is in the middle of a chain of text analysis tools where all the other tools may be finite-state-based (which is the case with text processing tools available from XEROX Corp.), converting the HMM into an FST makes this chain homogeneous, and thus enables merging the chain's components into one single FST, by means of composition.

In particular, it is possible to compose the HMM-derived transducer with, among others, one or more of the following transducers that encode:

- correction rules for the most frequent tagging errors in order to significantly improve tagging accuracy. These rules can either be extracted automatically from a corpus (Brill, 1992) or written manually (Chanod and Tapanainen, 1995). The rules may include long-distance dependencies which are usually not handled by HMM taggers.
- further steps of text analysis, e.g. light parsing or extraction of noun phrases or other phrases (Ait-Mokhtar and Chanod, 1997).
- criteria which decide on the relevance of a corpus with respect to a particular query in information retrieval (e.g. occurrence of particular words in particular syntactic structures).

These transducers can be composed separately or all at once (Kaplan and Kay, 1994). Such composition enables complex text analysis to be performed by a single transducer: see EP-A-583,083.

It will be appreciated that the algorithms described herein may find uses beyond those discussed with respect to the particular embodiments discussed below: i.e. on any kind of analysis of written or spoken language based on both finite-state technology and HMMs, such as corpus analysis, speech recognition, etc. The algorithms have been fully implemented.

Embodiments of the invention will now be described, by way of example, with reference to the accompanying drawings, in which:

Figure 1 illustrates decisions on tags with an n-type transducer, according to one embodiment of the invention;

Figure 2 illustrates schematically the generation of an n-type transducer in accordance with an embodiment of the invention;

Figure 3 illustrates the procedure of building an n-type transducer in accordance with an embodiment of the invention;

5 Figure 4 is a diagram illustrating class subsequences of a sentence;

Figure 5 is a schematic diagram of the steps in the procedure of building an s-type transducer, in accordance with an alternative embodiment of the invention;

Figure 6 is a diagram illustrating the disambiguation of classes between two selected tags;

10 Figure 7 is a diagram illustrating valid paths through the tag space of a sentence.

Figure 8 is a diagram illustrating b-type sequences.

Figure 9 is a schematic flow chart illustrating the procedure of building a b-type transducer;

15 Figure 10 is an illustration of the tagging of a sentence using either the n-type transducer formed in Fig. 3 or the s-type transducer formed in Fig. 5 or the b-type transducer formed in Fig. 9; and

Figure 11 is a schematic flow chart of the steps involved in the procedure, in accordance with an embodiment of the invention, of tagging a text corpus with a finite state tagger using an HMM transducer.

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#### **A. System configuration**

It will be appreciated that the techniques according to the invention may be employed using conventional computer technology. It will be appreciated that the invention may be implemented using a PC running Windows™, a Mac running MacOS, or a minicomputer running  
25 UNIX, which are well known in the art. For example, the PC hardware configuration is discussed in detail in *The Art of Electronics*, 2nd Edn, Ch. 10, P. Horowitz and W. Hill, Cambridge University Press, 1989. The invention has been implemented in C on a Sun Sparc 20 workstation running UNIX.

#### **30 B. FST derivation**

The invention will be described in by reference to three methods of deriving a transducer for part-of-speech tagging from an HMM. These methods and transducers are referred to herein as *n-type*, *s-type* and *b-type*.

35 An HMM used for tagging encodes, like a transducer, a relation between two languages. One language contains sequences of ambiguity classes obtained by looking up in a lexicon all the words of a sentence. The other language contains sequences of tags obtained by statistically disambiguating the class sequences. From outside, an HMM tagger behaves like a sequential transducer that deterministically maps every sequence of ambiguity classes (corresponding to a sentence) into a unique sequence of tags, e.g.:

[DET]	[ADJ,NOUN]	[ADJ,NOUN]	.....	[END]
DET	ADJ	NOUN	.....	END

### 5 C. n-Type Transducers

This section presents a method that approximates a first order Hidden Markov Model (HMM) by a finite state transducer (FST), referred to as an n-type approximation. Figure 1 illustrates decisions on tags with an n-type transducer, according to one embodiment of the invention.

10 As in a first order HMM we take into account initial probabilities  $\pi$ , transition probabilities  $a$  and class (i.e. observation symbol) probabilities  $b$ . However, probabilities over paths are not estimated. Unlike in an HMM, once a decision is made, it influences the following decisions but is itself irreversible.

Figure 1 illustrates this behaviour with an example: for the class  $c_1$  of word  $w_1$ , tag  $t_{12}$  is  
 15 selected which is the most likely tag in an initial position. For word  $w_2$ , the tag  $t_{22}$ , the most likely tag, is selected given class  $c_2$  and the previously selected tag  $t_{12}$ , etc.

A transducer encoding this behaviour can be generated as illustrated in Fig. 2: this shows schematically an n-type transducer in accordance with an embodiment of the invention. In this example there is a set of three classes,  $c_1$  with the two tags  $t_{11}$  and  $t_{12}$ ,  $c_2$  with the three tags  
 20  $t_{21}$ ,  $t_{22}$  and  $t_{23}$ , and  $c_3$  with one tag  $t_{31}$ . Different classes may contain the same tag, e.g.  $t_{12}$  and  $t_{23}$  may refer to the same tag (e.g. [NOUN]). Figure 3 illustrates the procedure of building an n-type transducer in accordance with an embodiment of the invention.

Starting with the set of tags and the set of classes (generally designated 2), for every possible pair of a class and a tag (e.g.  $c_1:t_{12}$  or [ADJ,NOUN]:NOUN) a unique state is created  
 25 (step s1) and labelled with this same pair. This set of states will allow to map any class to anyone of its tags. An initial state which does not correspond with any pair, is also created in step s1. All states are final, marked by double circles. This produces a set of states labelled with class-tag pairs and 1 initial state (generally designated 4).

For every state, as many outgoing arcs are created (step s2) as there are classes (three  
 30 in Fig. 2). Each such arc for a particular class points to the most probable pair of this same class. The set of outgoing arcs of one state will allow to decide on the following tag, based on the following class and the current state's tag. If the arc comes from the initial state, the most probable pair of a class and a tag (destination state) is estimated by the initial and class probability of the tag:

$$35 \quad \arg \max_k p_1(c_i, t_{ik}) = \pi(t_{ik}) \cdot b(c_i | t_{ik})$$

If the arc comes from a state other than the initial state, the most probable pair is estimated by the transition and class probability of the tag:

$$\arg \max_k p_2(c_i, t_{ik}) = a(t_{ik} | t_{previous}) \cdot b(c_i | t_{ik})$$

In the example (Fig. 2),  $c_1:t_{12}$  is the most likely pair of class  $c_1$ , and  $c_2:t_{23}$  the most likely pair of class  $c_2$  when coming from the initial state, and  $c_2:t_{21}$  the most likely pair of class  $c_2$  when coming from the state of  $c_3:t_{31}$ .

Every arc is labelled with the same symbol pair as its destination state, with the class symbol in the upper language and the tag symbol in the lower language. E.g. every arc leading to the state of  $c_1:t_{12}$  is labelled with  $c_1:t_{12}$ . The result is the non-minimal and non-deterministic FST

6. Finally, all state labels can be deleted since the behaviour described above is encoded in the arc labels and the network structure. The network can be minimised and determinised (step s3) to produce the  $n$ -type FST 8.

The above mathematical model is referred to as an  $n1$ -type model, the resulting finite-state transducer an  $n1$ -type transducer and the whole algorithm leading from the HMM to this transducer, an  $n1$ -type approximation of a first order HMM.

Adapted to a second order HMM, this algorithm would give an  $n2$ -type approximation.

Every  $n$ -type transducer is sequential, i.e. deterministic on the input side. In every state there is exactly one outgoing arc for every class symbol. An  $n$ -type transducer tags any corpus deterministically.

#### D. s-Type Transducers

This section presents a method, according to another embodiment of the invention, that approximates a first order Hidden Markov Model (HMM) by a finite state transducer (FST), referred to herein as an  $s$ -type approximation.

##### D.1 Mathematical Background

To tag a sentence i.e. to map its class sequence to the most probable tag sequence, one can split the class sequence at the unambiguous classes (containing one tag only) into subsequences, then tag them separately and concatenate them again. The result is equivalent to the one obtained by tagging the sentence as a whole.

Figure 4 is a diagram illustrating class subsequences of a sentence. Two types of subsequences of classes are distinguished: initial and middle ones. The final subsequence of a sentence is equivalent to a middle one, if it is assumed that the sentence end symbol (., or ! or ?)

always corresponds to an unambiguous class  $c_U$ .

An initial subsequence  $C_i$  starts with the sentence initial position and has any number (incl. zero) of ambiguous classes and ends with the first unambiguous class  $c_u$  of the sentence. It can be described by the regular expression:

$$C_i = c_a^* c_u$$

- 5 Given an initial class subsequence  $C_i$  of length  $r$ , its joint probability together with a corresponding initial tag subsequence  $T_i$  can be estimated by:

$$p(C_i, T_i) = \pi(t_1) \cdot b(c_1 | t_1) \cdot \left[ \prod_{j=2}^{r-1} a(t_j | t_{j-1}) \cdot b(c_j | t_j) \right] \cdot a(t_r | t_{r-1})$$

- 10 A middle subsequence  $C_m$  starts immediately after an unambiguous class  $c_u$ , has any number (incl. zero) of ambiguous classes  $c_a$  and ends with the following unambiguous class  $c_u$ . It can be described by the regular expression:

$$C_m = c_a^* c_u$$

- To estimate the probability of middle tag sequences  $T_m$  correctly, we have to include the  
 15 immediately preceding unambiguous class  $c_u^\theta$  actually belonging to the preceding subsequence  $C_i$  or  $C_m$ . Thus we obtain an extended middle subsequence:

$$C_m^\theta = c_u^\theta c_a^* c_u$$

The joint probability of an extended middle class subsequence  $C_m^\theta$  of length  $s$  together with a corresponding tag subsequence  $T_m^\theta$  can be estimated by

20 
$$p(C_m^\theta, T_m^\theta) = \left[ \prod_{j=1}^{s-1} a(t_j | t_{j-1}) \cdot b(c_j | t_j) \right] \cdot a(t_s | t_{s-1})$$

## D.2 Building an s-type transducer

To build an s-type transducer, we generate a large number of initial class sequences  $C_i$  and extended middle class sequences  $C_m^e$  as described in D.3 below, and disambiguate (i.e. tag) each of them based on a first order HMM using the Viterbi algorithm for efficiency (Viterbi, 1967; Rabiner, 1990).

Every class subsequence gets linked to its most probable tag subsequence by means of the cross product operation:

$$S_i = C_i \cdot x. T_i = c_1: t_1 \quad c_2: t_2 \quad \dots \quad c_n: t_n$$

$$S_m^e = C_m^e \cdot x. T_m^e = c_1^e: t_1^e \quad c_2^e: t_2^e \quad \dots \quad c_n^e: t_n^e$$

Then the union  $\bigcup S_i$  of all initial subsequences  $S_i$  and the union  $\bigcup S_m^e$  of all extended middle subsequences  $S_m^e$  is built.

In all extended middle subsequences  $S_m^e$ , like e.g.

$$S_m^e = \frac{C_m^e}{T_m^e} = \frac{[\text{DET}] [\text{ADJ}, \text{NOUN}] [\text{ADJ}, \text{NOUN}] [\text{NOUN}]}{\text{DET} \quad \text{ADJ} \quad \text{ADJ} \quad \text{NOUN}}$$

the first class symbol on the upper side and the first tag symbol on the lower side will be marked as an extension that does not really belong to the middle sequence but is necessary to disambiguate it correctly. The above example becomes

$$S_m^0 = \frac{C_m^0}{T_m^0} = \frac{0. [\text{DET}] [\text{ADJ}, \text{NOUN}] [\text{ADJ}, \text{NOUN}] [\text{NOUN}]}{0. \text{DET} \quad \text{ADJ} \quad \text{ADJ} \quad \text{NOUN}}$$

Now it is possible to formulate a preliminary sentence model containing one initial subsequence followed by any number (incl. zero) of extended middle subsequences:

$$U_S^0 = U_{S_i} \quad U_{S_m^0}^*$$

where all middle subsequences  $S_m^0$  are still marked and extended in the sense that all occurrences of all unambiguous classes are mentioned twice: Once at the end of every sequence (unmarked) and also at the beginning of every following sequence (marked).

To ensure a correct concatenation of initial and middle subsequences a concatenation constraint for classes is formulated:

$$R_c = \bigcap_j [ \sim \$ [ \setminus c_u \quad c_u^0 ] ]_j$$

stating that every middle subsequence must begin with the same marked unambiguous class  $c_U^0$  (e.g. 0.[DET]) that occurs unmarked as  $c_U$  (e.g. [DET]) at the end of the preceding subsequence since both symbols refer to the same occurrence of this unambiguous class.

Having ensured correct concatenation by composition of the preliminary sentence model  $U^0$   $S$  with the concatenation constraint  $R_C$ , all marked classes on the upper side and all marked tags on the lower side of the relation are deleted.

The above mathematical model is referred to as an *s-type model*, the corresponding finite-state transducer an *s-type transducer* and the whole algorithm leading from the HMM to the transducer, an *s-type approximation* of an HMM.

10 An s-type transducer tags any corpus that does not contain unknown subsequences exactly the same way, i.e. with the same errors, as the corresponding HMM tagger does. An s-type transducer is, however, incomplete because it encodes only a limited set of subsequences of ambiguity classes. Therefore an s-type transducer cannot tag sentences with one or more subsequences that are not in this set. An s-type transducer can be completed as described in D.4  
15 below.

### D.3 Generation of ambiguity class subsequences

This section describes three ways to obtain class subsequences that are needed to build an s-type transducer. Figure 5 is a schematic diagram of the steps in the procedure of building an  
20 s-type transducer, in accordance with an alternative embodiment of the invention.

#### (a) Extraction from a corpus

Based on a lexicon and a guesser an untagged training corpus (10) is annotated with class labels, exactly the same way as is done later for the purpose of tagging.

From every sentence we extract (step s4) the initial class subsequence  $C_i$  that ends with  
25 the first unambiguous class  $c_U$ , and all extended middle subsequences  $C_m^0$  ranging from any unambiguous class  $c_U$  in the sentence to the following unambiguous class. This generates the incomplete set of class subsequences (s-type), designated 12.

#### (b) Generation of all possible subsequences

Here, the set of tags and set of classes (generally designated 2) is used as the starting  
30 point. The set of all classes  $c$  is split into the subset of unambiguous classes  $c_U$  and the subset of ambiguous classes  $c_A$ . Then all possible initial and extended middle class subsequences,  $C_i$  and  $C_m^e$  up to a defined length are generated (step s5).

As in D.3(a), an incomplete set of class sequences (s-type) 12 is obtained, and the HMM can be used (step s7) to obtain from this an incomplete set of class and tag sequences (s-type)  
35 14. This set 14 can be used with finite state calculus to build (step s8) an s-type transducer 16;

and this incomplete s-type FST in turn is used to derive the incomplete set 14, through extraction (step s10) of all class sequences.

#### (c) Extraction from a transducer

If an n-type transducer  $N$  approximating an HMM is already available, initial and extended middle class and tag subsequences,  $S_i$  and  $S_m^e$  can be extracted (step s6) using finite state calculus, to produce a complete set 17 of class and tag sequences (n-type).

#### D.4 Completion of s-type transducers

s-Type transducers with class subsequences that have been generated as described in D.3(a) or D.3(b) above, are in general not complete on the input side. They do not accept all possible ambiguity class sequences. This, however, is necessary for a transducer used to disambiguate class sequences of any corpus since a new corpus can contain sequences not encountered in the training corpus.

An incomplete s-type transducer  $S$  can be completed (step s12) with subsequences from an auxiliary complete n-type transducer  $N$  as follows:

First, the unions of initial and extended middle subsequences,  $U_{S_i}$  and  $U_{S_m^e}$  are extracted from the primary s-type transducer  $S$ , and the unions  $U_{N_i}$  and  $U_{N_m^e}$  are extracted from the auxiliary n-type transducer  $N$ , as described in section D.3(c) above.

Then a joint union  $U_{S_i}$  of initial subsequences is made:

$$U_{S_i} = U_{S_i} \cup [ [ U_{N_i} \cdot U_{S_i} ] \cdot U_{S_i} ]$$

and a joint union  $U_{S_m^e}$  of extended middle subsequences:

$$U_{S_m^e} = U_{S_m^e} \cup [ [ U_{N_m^e} \cdot U_{S_m^e} ] \cdot U_{S_m^e} ]$$

In both cases all subsequences from the principal model  $S$  are unioned with all those subsequences from the auxiliary model  $N$  that are not in  $S$ .

Finally, the complete s+n-type transducer 18 is generated (step s14) from the joint unions of subsequences  $U_{S_i}$  and  $U_{S_m^e}$ , as described in section D.2 above.

A transducer completed in this way disambiguates all subsequences known to the principal incomplete s-type model exactly as the underlying HMM does, and all other subsequences as the auxiliary n-type model does.

#### E. b-Type Transducers

This section presents a method, according to another embodiment of the invention, that approximates a first order Hidden Markov Model (HMM) by a finite-state transducer (FST), referred to herein as b-type approximation. Regular expression operators used in this section are explained in the annex.

### E.1 Basic Idea

Tagging of a sentence based on a (first order) HMM includes finding the most probable tag sequence given the class sequence of the sentence.

5 In this approach, an ambiguity class is disambiguated with respect to a context. A context consists of a sequence of ambiguity classes limited at both ends by some selected tag. For the left context of length  $\beta$  we use the term *look-back*, and for the right context of length  $\alpha$  we use the term *look-ahead*.

10 In Fig. 6, the tag  $t_i^2$  can be selected from the class  $c_i$  because it is between two selected tags which are  $t_{i-2}^1$  at a look-back distance of  $\beta=2$  and  $t_{i+2}^2$  at a look-ahead distance of  $\alpha=2$ . Actually, the two selected tags  $t_{i-2}^1$  and  $t_{i+2}^2$  allow not only the disambiguation of the class  $c_i$  but of all classes inbetween, i.e.  $c_{i-1}$ ,  $c_i$  and  $c_{i+1}$ .

15 We approximate the tagging of a whole sentence by tagging sub-sequences with selected tags at both ends (Fig. 6), and then overlapping them. The most probable paths in the tag space of a sentence, i.e. valid paths according to this approach, can be found as sketched in Fig. 7. An ordered set of overlapping sequences where every sequence is shifted by one tag to the right with respect to the previous sequence, constitutes a valid path. There can be more than one valid path in the tag space of a sentence (Fig. 7). Sets of sequences that do not overlap in such a way are incompatible according to this model, and do not constitute valid paths.

20

### E.2 b-Type Sequences

Given a length  $\beta$  of look-back and a length  $\alpha$  of look-ahead, we generate for every class  $c_0$ , every look-back sequence  $t_{-\beta} c_{-\beta+1} \dots c_{-1}$ , and every look-ahead sequence  $c_1 \dots c_{\alpha-1} t_{\alpha}$ , a b-type sequence:

25 
$$t_{-\beta} c_{-\beta+1} \dots c_{-1} c_0 c_1 \dots c_{\alpha-1} t_{\alpha}$$

For example:

CONJ [DET,PRON] [ADJ,NOUN,VERB] [NOUN,VERB] VERB

Each such *original b-type sequence* (Fig. 8) is disambiguated based on a first order HMM. Here we use the Viterbi algorithm (Viterbi, 1967; Rabiner, 1990) for efficiency.

30 The algorithm will be explained for a first order HMM. In the case of a second order HMM, b-type sequences must begin and end with two selected tags rather than one.

For an original *b-type sequence*, the joint probability of its class sequence  $C$  with its tag sequence  $T$  (Fig. 8), can be estimated by:

$$p(C,T) = p(c_{-\beta+1} \dots c_{\alpha-1}, t_{-\beta} \dots t_{\alpha}) = \left[ \prod_{i=-\beta+1}^{\alpha-1} a(t_i | t_{i-1}) b(c_i | t_i) \right] \cdot a(t_{\alpha} | t_{\alpha-1})$$

A boundary, i.e. a sentence beginning or end, may occur position in the look-back sequence and in the look-ahead sequence. No look-back ( $\beta=0$ ) or no look-ahead ( $\alpha=0$ ) is also allowed. The above probability estimation can then be expressed more generally (Fig. 8) as:

$$p(C,T) = p_{start} \cdot p_{middle} \cdot p_{end}$$

with  $p_{start}$  being

$$p_{start} = a(t_{-\beta+1} | t_{-\beta}) \quad \text{for fixed tag } t_{-\beta}$$

$$p_{start} = \pi(t_{-\beta+1}) \quad \text{for sentence beginning \#}$$

$$p_{start} = 1 \quad \text{for } \beta = 0, \text{ i.e. no look-back}$$

10 with  $p_{middle}$  being

$$p_{middle} = b(c_{-\beta+1} | t_{-\beta+1}) \cdot \prod_{i=-\beta+2}^{\alpha-1} a(t_i | t_{i-1}) b(c_i | t_i) \quad \text{for } \beta + \alpha > 0$$

$$p_{middle} = b(c_0 | t_0) \quad \text{for } \beta + \alpha = 0$$

and with  $p_{end}$  being

$$p_{end} = a(t_{\alpha} | t_{\alpha-1}) \quad \text{for fixed tag } t_{\alpha}$$

$$p_{end} = 1 \quad \text{for sentence end \# or } \alpha = 0, \text{ i.e. no look-ahead}$$

When the most likely tag sequence is found for an original b-type sequence, the class  $c_0$  in the middle position is associated with its most likely tag  $t_0$ . We formulate constraints for the other tags  $t_{-\beta}$  and  $t_{\alpha}$  and classes  $c_{-\beta+1} \dots c_{-1}$  and  $c_1 \dots c_{\alpha-1}$  of the original b-type sequence. Thus  
20 we obtain a *tagged b-type sequence*:

$$t_{-\beta} \ c_{-\beta+1} \dots c_{-1} \ c_0: t_0 \ c_1 \dots c_{\alpha-1} \ t_{\alpha}$$

stating that  $t_0$  is the most probable tag in the class  $c_0$  if it is preceded by  $t_{-\beta} \ c_{-\beta+1} \dots c_{-1}$  and

followed by  $c_1 \dots c_{\alpha-1} \ t_{\alpha}$

In the example:

CONJ-B2 [DET,PRON]-B1 [ADJ,NOUN,VERB]:ADJ [NOUN,VERB]-A1 VERB-A2

ADJ is the most likely tag in the class [ADJ,NOUN,VERB] if it is preceded by the tag CONJ two positions back (B2), by the class [DET,PRON] one position back (B1), and followed by the class [NOUN,VERB] one position ahead (A1) and by the tag VERB two positions ahead (A2).

- 5 Boundaries are denoted by a particular symbol, #, and can occur anywhere in the look-back and look-ahead. For example:

#-B2 [DET,PRON]-B1 [ADJ,NOUN,VERB]:ADJ [NOUN,VERB]-A1 VERB-A2

CONJ-B2 [DET,PRON]-B1 [ADJ,NOUN,VERB]:NOUN #-A1

- 10 Note that look-back length  $\beta$  and look-ahead length  $\alpha$  also include all sequences shorter than  $\beta$  or  $\alpha$ , respectively, that are limited by a boundary #.

Figure 9 is a schematic diagram illustrating the steps in the procedure of building a b-type transducer, according to an embodiment of the invention.

- For a given length  $\beta$  of look-back and a length  $\alpha$  of look-ahead, and using the set of tags and the set of classes, every possible *original b-type sequence* is generated (step s90). Then, these are disambiguated statistically, and encoded it in a *tagged b-type sequence*  $B_i$  as described above (Viterbi; step s92). All sequences  $B_i$  are then unioned and a preliminary tagger model  $B'$  generated (step s94):

$$B' = \left[ \bigcup_i B_i \right]^*$$

- where all sequences  $B_i$  can occur in any order and number (including zero times) because no constraints have yet been applied.

### E.3 Concatenation Constraints

- To ensure a correct concatenation of sequences, it is necessary to make sure that every sequence  $B_i$  is preceded and followed by other  $B_j$  according to what is encoded in the look-back and look-ahead which were explained above.

Constraints are created for preceding and following tags, classes and sentence boundaries. For the look-back, a particular tag  $t_i$  or class  $c_j$  is requested for a particular distance of  $\delta \leq -1$ , by:

$$R^\delta(t_i) = \sim [ \sim [ ?^* t_i [ \cup t ]^* [ \cup t [ \cup t ]^* ]^{(-\delta-1)} t_i^{B(-\delta)} ?^* ]$$

$$R^\delta(c_j) = \sim [ \sim [ ?^* c_j [ \cup c ]^* [ \cup c [ \cup c ]^* ]^{(-\delta-1)} c_j^{B(-\delta)} ?^* ]$$

for  $\delta \leq -1$ 

with  $\cup t$  and  $\cup c$  being the union of all tags and all classes respectively. A sentence beginning, #, is requested for a particular look-back distance of  $\delta \leq -1$ , by:

$$R^\delta(\#) = \sim [\sim [\cup t]^* [\cup t \cup t]^*]^{(-\delta-1)} \#^{B(-\delta)} ?^*]$$

5

for  $\delta \leq -1$ 

In the case of look-ahead, for a particular distance of  $\delta \geq 1$ , a particular tag  $t_i$  or class  $c_j$  or a sentence end # is required in a similar way, by:

$$R^\delta(t_i) = \sim [?^* t_i^{A\delta} \sim [\cup t]^* [\cup t \cup t]^*]^{(\delta-1)} t_i ?^*]$$

$$R^\delta(c_j) = \sim [?^* c_j^{A\delta} \sim [\cup c]^* [\cup c \cup c]^*]^{(\delta-1)} c_j ?^*]$$

10

$$R^\delta(\#) = \sim [?^* \#^{A\delta} \sim [\cup t]^* [\cup t \cup t]^*]^{(\delta-1)}]$$

for  $\delta \geq 1$ 

We create the intersection  $R_t$  of all tag constraints  $R^\delta(t_i)$ , the intersection  $R_c$  of all class constraints  $R^\delta(c_j)$ , and the intersection  $R_\#$  of all sentence boundary constraints  $R^\delta(\#)$ :

$$R_t = \bigcap_{\delta, i} R^\delta(t_i)$$

15

$$R_c = \bigcap_{\delta, j} R^\delta(c_j)$$

$$R_\# = \bigcap_{\delta} R^\delta(\#)$$

All constraints (for tags, classes and sentence boundaries) are enforced (step s96 in Fig. 9) by composition with the preliminary tagger model  $B'$ . The class constraint  $R_c$  must be composed on the upper side of  $B'$  which is the side of the classes, and both the tag constraint  $R_t$  and the boundary constraint  $R_\#$  must be composed on the lower side of  $B'$  which is the side of the tags:

$$B'' = R_c \circ B' \circ R_t \circ R_\#$$

Having ensured correct concatenation, all symbols that have served to constrain tags, classes or boundaries are deleted (from  $B^*$ ) (step s98). Finally, the FST is determinized and minimized.

- 5        The above-mentioned mathematical model is referred to as a *b-type model*, the corresponding FST as a *b-type transducer*, and the whole algorithm leading from the HMM to the transducer, as a *b-type approximation* of an HMM.

#### E.4 Properties of b-Type Transducers

- 10       There are two groups of b-type transducers with different properties: FSTs without look-back or without look-ahead and FSTs with both look-back and look-ahead. Both accept any sequence of ambiguity classes.

      b-Type FSTs without look-back or without look-ahead are always sequential. They map a class sequence that corresponds to the word sequence of a sentence, always to exactly one tag sequence. Their tagging accuracy and similarity with the underlying HMM increases with growing look-back or look-ahead. A b-type FST with look-back  $\beta=1$  and without look-ahead ( $\alpha=0$ ) is equivalent to an n1-type FST (section C).

- b-Type transducers with both look-back and look-ahead are in general not sequential. For a class sequence corresponding to the word sequence of a sentence, they deliver a set of alternative tag sequences, which means that the tagging results are ambiguous. This set is never empty, and the most probable tag sequence according to the underlying HMM is always in this set. The longer the look-back distance  $\beta$  and the look-ahead distance  $\alpha$  are, the larger the FST and the smaller the set of alternative tagging results. For sufficiently large look-back plus look-ahead, this set may contain always only one tagging result. In this case the b-type FST is equivalent to the underlying HMM. For reasons of size however, this FST is only computable for HMMs with small tag sets.

#### F. An Implemented Finite State Tagger

- The implemented tagger requires three transducers which represent a lexicon, a guesser and an approximation of an HMM. Figure 10 is an illustration of the tagging of a sentence using either the n-type transducer of Fig. 3, the s-type transducer formed in Fig. 5 or the b-type transducer formed in Fig. 9. Figure 11 is a schematic flow chart of the steps involved in the procedure, in accordance with an embodiment of the invention, of tagging a text corpus 20 with a finite state tagger using an HMM transducer.

- 35       Every word 21 of an input sentence is read (step s71) from the corpus and is initially looked for in the lexicon; and if this fails, the search continues in the guesser (step s72), resulting in a word labelled with a class (22). As soon as an input token gets labelled with the sentence end class (e.g. [SENT] in Fig. 10), the tagger stops (step s73) reading words from the input. At that point the tagger has read and stored the words of a whole sentence (Fig. 6, col. 1) and generated
- 40       the corresponding sequence of classes 23 (see Fig. 10, col. 2).

The class sequence 23 is now deterministically mapped (step s74) to a tag sequence 24 (see Fig. 10, col. 3) by means of the HMM transducer.

The tagger outputs (step s75) the stored word and tag sequence 24 of the sentence and continues (step s76) the same way with the remaining sentences of the corpus, stopping (step s77) when the end of the corpus is reached. The end result is the tagged text corpus 25.

#### G. Tests and Results

Table 1 compares an n-type and an s-type transducer with the underlying HMM on an English test case. As expected, the transducers perform tagging faster than the HMM.

	tagging accuracy in %	tagging speed on different computers in words/sec		transducer size	
		on ULTRA2	on SPARC20	num. states	num. arcs
HMM	96.77	4 590	1 564	none	none
s-type transducer	95.05	12 038	5 453	4 709	976 785
n-type transducer	94.19	17 244	8 180	71	21 087

Language:	English
HMM training corpus:	19 944 words
Test corpus:	19 934 words
Tag set:	74 tags 297 classes
s-Type transducer	with subsequences from a training corpus of 100,000 words completed with subsequences from an n-type transducer

Table 1: Accuracy, speed, size and creation time of HMM transducers

Since both transducers are approximations of HMMs, they show a slightly lower tagging accuracy than the HMMs. However, improvement in accuracy can be expected since these transducers can be composed with transducers encoding correction rules for frequent errors, as described above in the introductory part of this disclosure.

The s-type transducer is more accurate in tagging but also larger and slower than the n-type transducer.

Table 2 compares the tagging accuracy of n-type and s-type transducers and the underlying HMM for different languages.

	Tagging accuracy in %					
	English	Dutch	French	German	Portug.	Spanish
HMM	96.77	94.76	98.65	97.62	97.12	97.60
s-type transducer	95.05	92.36	98.37	95.81	96.56	96.87
n-type transducer	94.19	91.58	98.18	94.49	96.19	96.46

s-Type transducer with subsequences from a training corpus of 100,000 words  
completed with subsequences from n-type transducer

Table 2: Accuracy of HMM transducers for different languages

5

For the test of b-type transducers we used an English corpus, lexicon and guesser, that originally were annotated with 74 different tags. We automatically recoded the tags in order to reduce their number, i.e. in some cases more than one of the original tags were recoded into one and the same new tag. We applied different recodings, thus obtaining English corpora, lexicons and guessers with reduced tag sets of 45, 36, 27, 18 and 9 tags respectively.

10

Transducer or HMM	Accuracy	Tagging speed		Transducer size		Creation
	test corp.	in words/second		num.of	num.of	time
	in %	on Ultra2	onSparc20	states	arcs	on Ultra2
HMM	97.07	3 358	1 363	_____	_____	_____
b-FST ( $\beta=0,\alpha=0$ )	94.47	25 521	11 815	1	119	3 sec
b-FST ( $\beta=1,\alpha=0$ )	95.60	25 521	12 038	28	3 332	4 sec
b-FST ( $\beta=2,\alpha=0$ )	97.71	25 521	11 193	1 642	195 398	32 min
b-FST ( $\beta=0,\alpha=1$ )	95.26	17 244	9 969	137	14 074	5 sec
b-FST ( $\beta=0,\alpha=2$ )	95.37	19 939	9 969	3 685	280 545	3 min
b-FST ( $\beta=1,\alpha=1$ )	*96.78	16 790	8 986	1 748	192 275	19 sec
b-FST ( $\beta=2,\alpha=1$ )	*97.06	22 787	11 000	19 878	1 911 277	61 min

Language	English
Corpora	19 944 words for HMM training, 19 934 words for test
Tag set	27 tags, 119 classes
•	Multiple, i.e. ambiguous tagging results: Only first result retained
Types of FST (Finite State Transducers)	
b ( $\beta=2, \alpha=1$ )	b-type transducer with look-back of 2 and look-ahead of 1
Computers	
Ultra2	1 CPU, 512 MBytes physical RAM, 1.4 GBytes virtual RAM
Sparc20	1 CPU, 192 MBytes physical RAM, 827 MBytes virtual RAM

Table 3: Accuracy, tagging speed and size of some HMM transducers

Table 3 compares b-type transducers with different length of look-back and look-ahead for a tag set of 27 tags. The highest accuracy (97.06 %) could be obtained with an b-type FST with  $\beta=2$  and  $\alpha=1$ . This b-type FST produced in some cases ambiguous tagging results. Then only the first result found was retained.

5

Transducer or HMM	Tagging accuracy with tag sets of different sizes (in %)					
	74 tags 297 cls.	45 tags 214 cls.	36 tags 181 cls.	27 tags 119 cls.	18 tags 97 cls.	9 tags 67 cls.
HMM	96.78	96.92	97.35	97.07	96.73	95.76
b-FST ( $\beta=0, \alpha=0$ )	83.53	83.71	87.21	94.47	94.24	93.86
b-FST ( $\beta=1, \alpha=0$ )	94.19	94.09	95.16	95.60	95.17	94.14
b-FST ( $\beta=2, \alpha=0$ )	—	94.28	95.32	95.71	95.31	94.22
b-FST ( $\beta=0, \alpha=1$ )	92.79	92.47	93.69	95.26	95.19	94.64
b-FST ( $\beta=0, \alpha=2$ )	93.46	92.77	93.92	95.37	95.30	94.80
b-FST ( $\beta=1, \alpha=1$ )	*94.94	*95.14	*95.78	*96.78	*96.59	*95.36
b-FST ( $\beta=2, \alpha=1$ )	—	—	*97.34	*97.06	*96.73	*95.73
b-FST ( $\beta=3, \alpha=1$ )	—	—	—	—	—	95.76


Language	English
Corpora	19 944 words for HMM training, 19 934 words for test
Types of FST (Finite State Transducers)	see Table 3
•	Multiple, i.e. ambiguous tagging results: Only first result retained
	Transducer could not be computed for reasons of size.

Table 4: Tagging accuracy with tags sets of different sizes

Table 4 shows the tagging accuracy of different b-type transducers with tag sets of different sizes. To get results that are almost equivalent to those of an HMM, a b-type FST needs at least a look-back of  $\beta=2$  and a look-ahead of  $\alpha=1$  or vice versa. For reasons of size, this kind of FST could only be computed for the tag sets with 36 tags or less. A b-type FST with  $\beta=3$  and  $\alpha=1$  could only be computed for the tag set with 9 tags. This FST gave exactly the same tagging results as the underlying HMM.

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**Annex: Regular Expression Operators of the XEROX Finite State Calculus**

Below, *a* and *b* designate symbols, *A* and *B* designate languages, and *R* and *Q* designate relations between two languages. More details on the following operators and pointers to finite-state literature can be found in <http://www.rsrc.xerox.com/research/mltt/fst>

$\$A$	<b>Contains.</b> Set of strings containing at least one occurrence of a string from <i>A</i> as a substring.
$\neg A$	<b>Complement</b> (negation). All strings except those from <i>A</i> .
$\backslash a$	<b>Term complement.</b> Any symbol other than <i>a</i> .
$A^*$	<b>Kleene star.</b> Zero or more times <i>A</i> concatenated with itself.
$A^n$	<b>A n times.</b> Language <i>A</i> concatenated <i>n</i> times with itself.
$A^+$	<b>Kleene plus.</b> One or more times <i>A</i> concatenated with itself.
$a \rightarrow b$	<b>Replace.</b> Relation where every <i>a</i> on the upper side gets mapped to a <i>b</i> on the lower side.
$a \leftarrow b$	<b>Inverse replace.</b> Relation where every <i>b</i> on the lower side gets mapped to an <i>a</i> on the upper side.
$a:b$	<b>Symbol pair</b> with <i>a</i> on the upper and <i>b</i> on the lower side.
$R.u$	<b>Upper language</b> of the relation <i>R</i> .
$R.l$	<b>Lower language</b> of the relation <i>R</i> .
$R.i$	<b>Inverse relation</b> where the upper and the lower language are exchanged with respect to <i>R</i> .
$A \ B$	<b>Concatenation</b> of all strings of <i>A</i> with all strings of <i>B</i> .
$A \mid B$	<b>Union</b> of the languages <i>A</i> and <i>B</i> .
$A \ \& \ B$	<b>Intersection</b> of the languages <i>A</i> and <i>B</i> .
$A - B$	<b>Relative complement</b> (minus). All strings of the language <i>A</i> that are not in <i>B</i> .
$A \ .x. \ B$	<b>Cross Product</b> (Cartesian product) of the languages <i>A</i> and <i>B</i> .
$R \ .o. \ Q$	<b>Composition</b> of the relations <i>R</i> and <i>Q</i> .
$\emptyset$ or $[\ ]$	<b>Empty string</b> (epsilon).
$?$	<b>Any symbol</b> in the known alphabet and its extensions.

**CLAIMS:**

1. A method carried out in a text processing system, for generating a text tagging finite state transducer (FST) for a predetermined language, the finite state transducer encoding along a plurality of arcs sets of ordered pairs of upper and lower labels, comprising:
- (a) providing a set of tags, the or each tag being a part-of-speech designator for the language, and a set of classes, the or each class being ambiguity classes, defining groups of possible tags, for words in the language,
  - (b) providing a plurality of states, including an initial state and, for each class-tag pair, a further state labelled as the respective class-tag pair, and
  - (c) for each state, for each class, creating an arc between the state and a destination state labelled with a class-tag pair, the class tag pair being the most probable for the class, the arc so added having the class as its upper label and a tag of that class as its lower label.

2. The method of claim 1, wherein (c) comprises, where the state is the initial state, (c1) determining the most probable class tag pair using

$$\arg \max_k p_1(c_i, t_{ik}) = \pi(t_{ik}) \cdot b(c_i | t_{ik})$$

where  $\pi$  is initial probability, and  $b$  is class probability.

3. The method of claim 1 or 2, wherein (c) comprises, where the state is not the initial state, (c1') determining the most probable class tag pair using

$$\arg \max_k p_2(c_i, t_{ik}) = a(t_{ik} | t_{previous}) \cdot b(c_i | t_{ik})$$

where  $a$  is transition probability, and  $b$  is class probability.

4. The method of claim 1, 2 or 3, further comprising minimising and determinising the FST generated in steps (a)- (c).
5. A method carried out in a text processing system, for generating a text tagging finite state transducer (FST) for a predetermined language, the finite state transducer encoding along a plurality of arcs sets of ordered pairs of upper and lower labels, comprising:
- (a) providing an incomplete set of class sequences, the class sequences being sequences of classes, the or each class being ambiguity classes, defining groups of possible tags, for words in the language,
  - (b) tagging the class sequences using a Hidden Markov Model, to produce an incomplete set of class and tag sequences of a first type,
  - (c) providing a complete set of class and tag sequences of a second type,

- (d) combining the set of class and tag sequences of a first type with the set of class and tag sequences of a second type, and
  - (e) building a FST using the combination obtained in step (d).
- 5    6.    The method of claims 5, wherein step (a) comprises:
- (a1) providing a set of tags and a set of classes, and
  - (a2) creating from said set of tags and set of classes, all possible class sequences up to a predetermined length.
- 10    7.    The method of claim 5, wherein step (a) comprises:
- (a1') providing an untagged text corpus, and
  - (a2') extracting all class sequences from the untagged text corpus.
- 15    8.    The method of claim 5, 6 or 7, wherein step © comprises:
- (c1) providing a FST generated according to the method of any of claims 1 to 4,
  - (c2) extracting all class sequences from the FST provided in step (c1).
- 20    9.    A method carried out in a text processing system, for generating a text tagging finite-state transducer (FST) for a predetermined language, the FST encoding along a plurality of arcs sets of ordered pairs of upper and lower labels, comprising:
- (a) providing a set of tags, the or each tag being a part-of-speech designator for the language, and a set of classes, the or each class being an ambiguity class, defining groups of possible tags, for the language,
  - (b) creating from the set of tags and the set of classes a set of subsequences of ambiguity classes, said set of subsequences comprising all possible subsequences for a predetermined look-back value and look-ahead value,
  - (c) using a Hidden Markov Model, tagging said set of subsequences to generate a set of tagged subsequences,
  - (d) performing a union operation, followed by a Kleene star operation, on the set of tagged subsequences, to generate a preliminary tagger model, said preliminary tagger model being a sequence in which the tagged subsequences may appear in any order or in any number,
  - (e) composing a plurality of constraints with the preliminary tagger model to generate the tagging FST, said constraints including constraints for tags, classes and sentence boundaries, and deleting all symbols expressing constraints.
- 30    10.    A method carried out in a text processing system, for tagging an untagged text corpus, comprising:
- (a) reading, in sequence, the or each word of the text corpus,
- 35

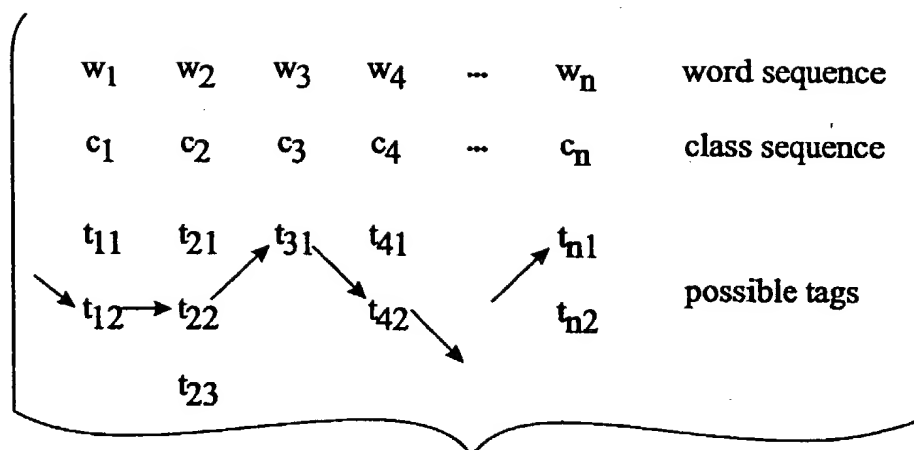
- (b) for the or each word, looking up the word using a lexical resource, to obtain the word labelled with its class,
- (c) if a sentence end token has not been read, repeating steps (a) and (b), the sentence end token defining the end of the current sentence,
- 5 (d) if a sentence end token has been read, applying the FST obtainable by the method of claims 1, 5 or 9 to the class sequence corresponding to the current sentence, to generate a tag sequence, the tag sequence comprising a sequence of tags,
- (e) outputting a tagged form of the current sentence, the tagged form comprising the or each word of the current sentence and, appended thereto, a respective tag from said tag sequence, and
- 10 (f) if the end of the text corpus has not been reached, repeating steps (a)-(e).

11. A text processing system when suitably programmed for carrying out the method of any of the preceding claims, the system comprising a processor and memory, the processor being

15 operable with said memory for executing instructions corresponding to steps of any of said methods.

12. A recordable medium having recorded thereon digital data defining instructions for execution by a processor and corresponding the steps of the methods of any of claims 1 to 10.

20

**FIG. 1**

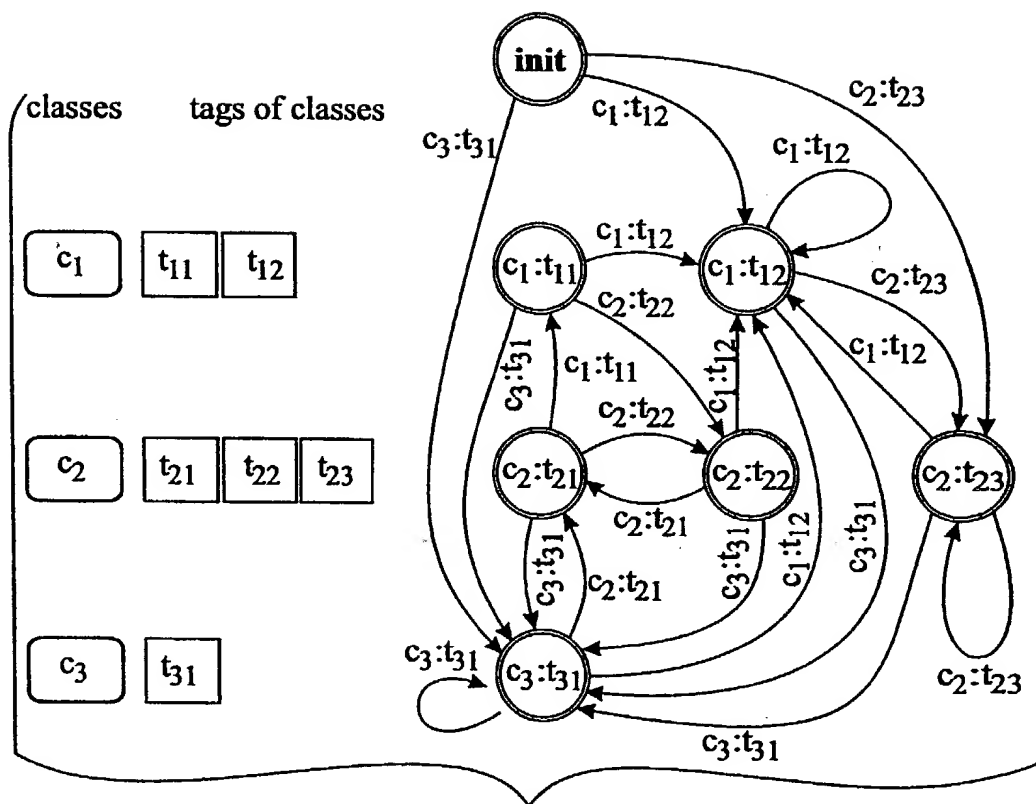
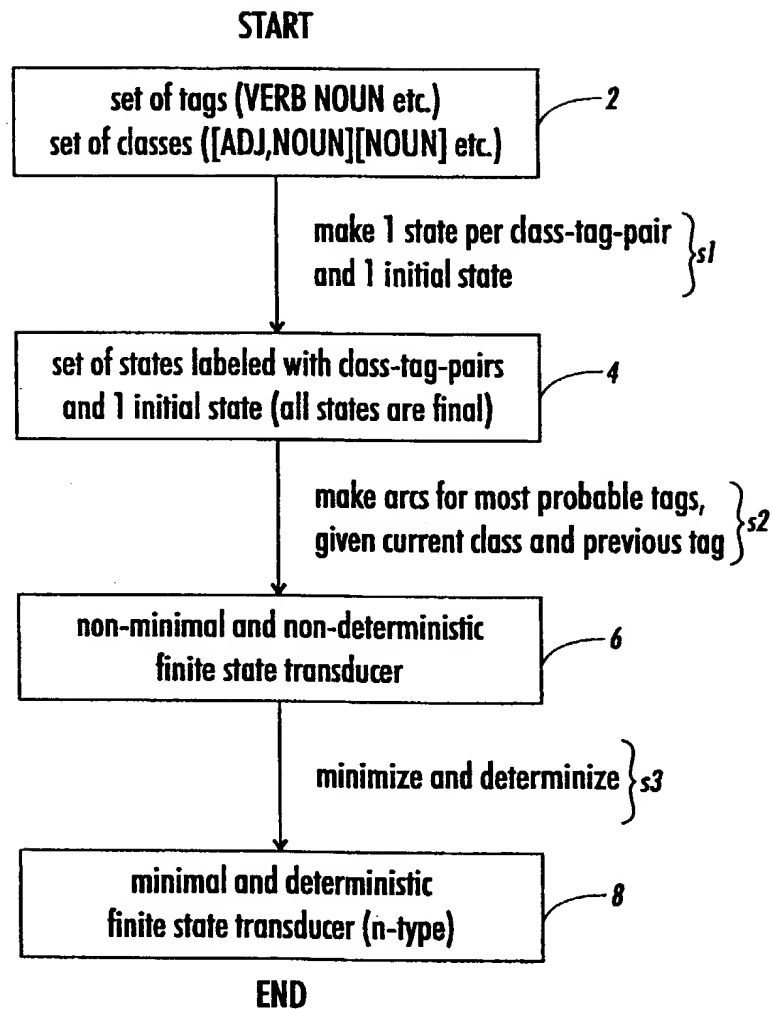
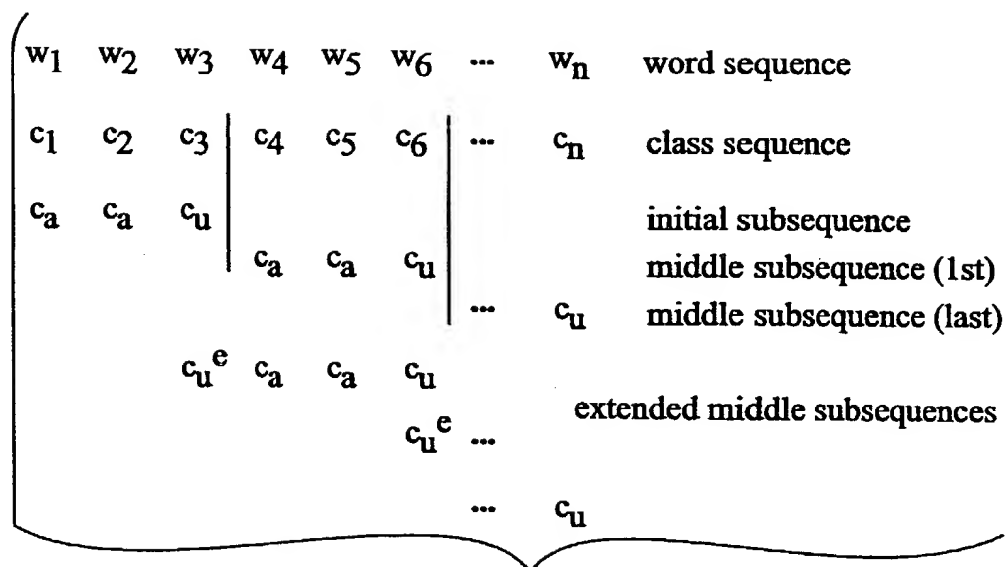


FIG. 2

**FIG. 3**

**FIG. 4**

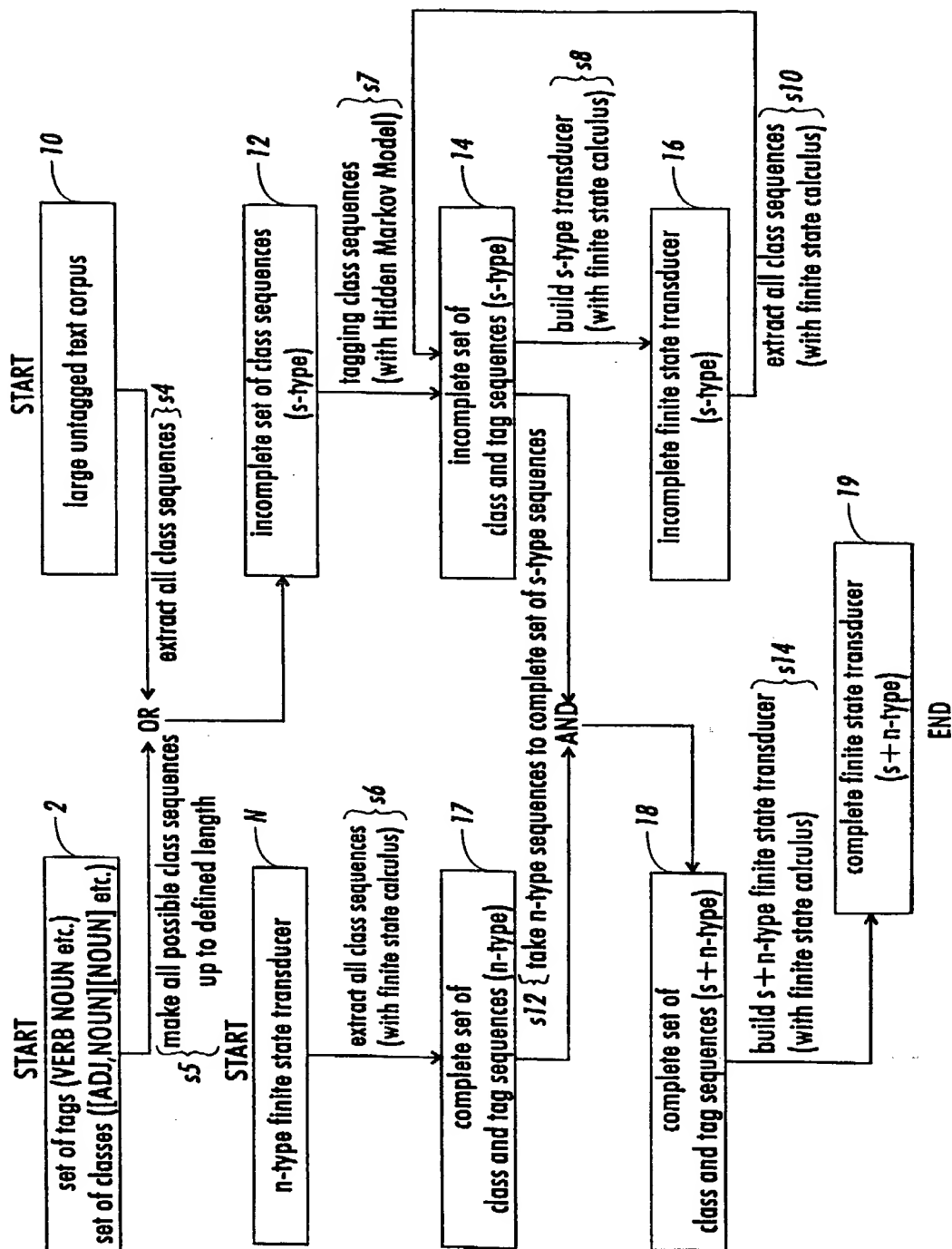
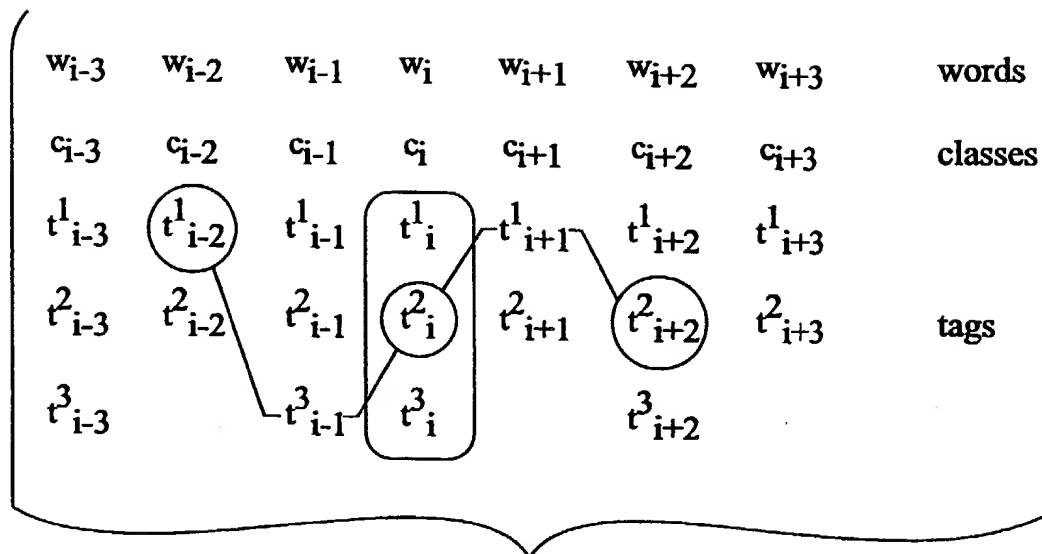
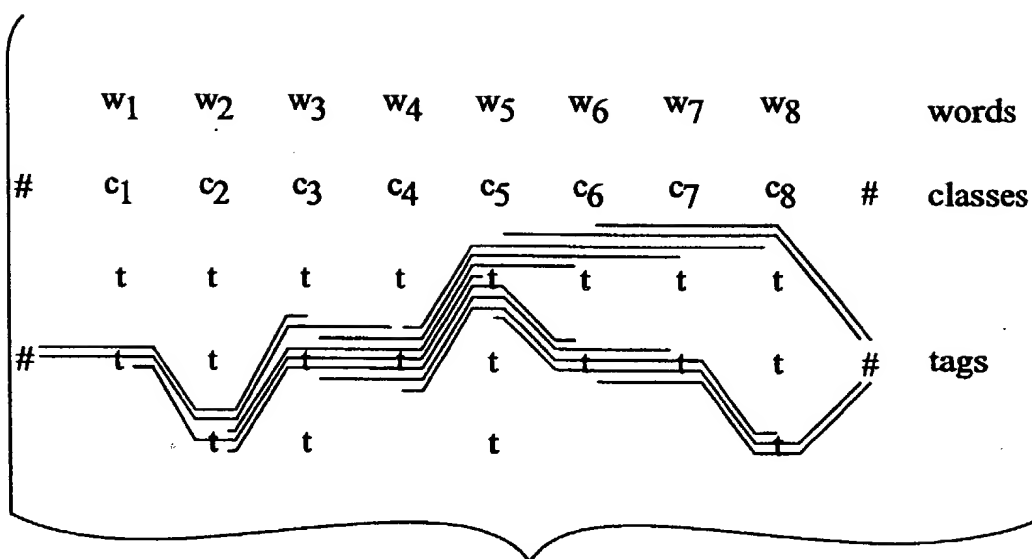


FIG. 5

**FIG. 6**

**FIG. 7**

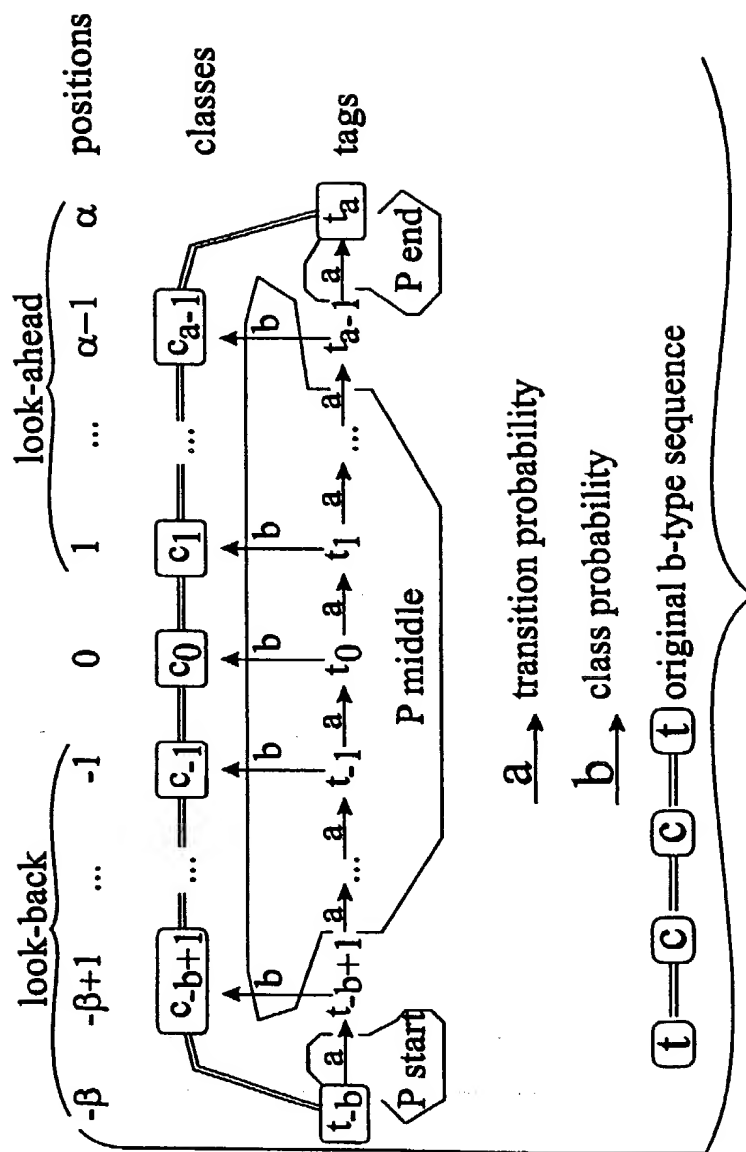


FIG. 8

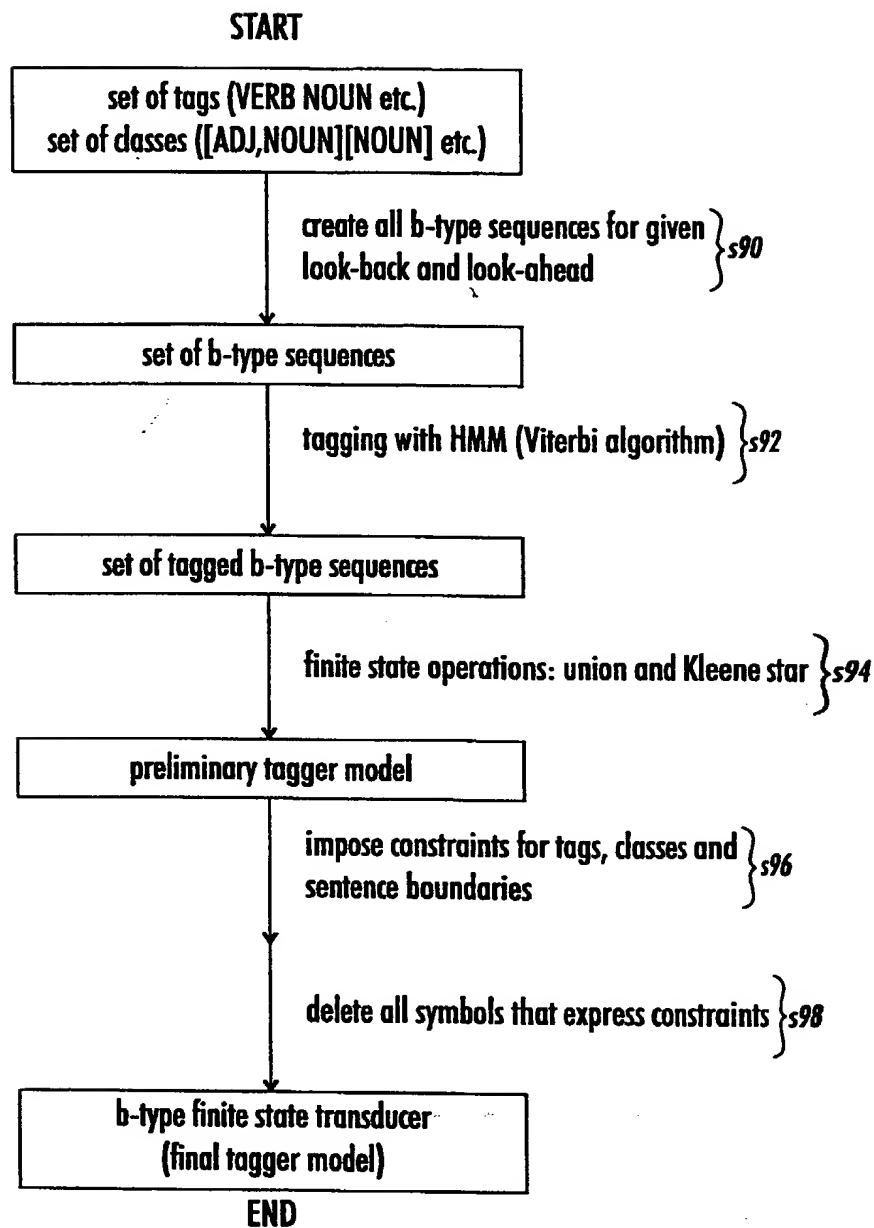


FIG. 9

The	[AT]	AT
share	[NN,VB]	NN
of	[IN]	IN
the	[AT]	AT
new	[JJ,RB]	JJ
housing	[NN,VBG]	NN
market	[NN,VB]	NN
enjoyed	[VBD,VCN]	VBD
by	[IN,RB]	IN
apartments	[NNS]	NNS
has	[HVZ]	HVZ
more	[AP,RB]	RB
than	[CS,IN]	CS
tripled	[VBD,VCN]	VBD
within	[IN,RB]	IN
that	[CS,DT,WPS]	DT
span	[NN,VB,VBD]	VBD
of	[IN]	IN
time	[NN,VB]	NN
.	[SENT]	SENT

FIG. 10

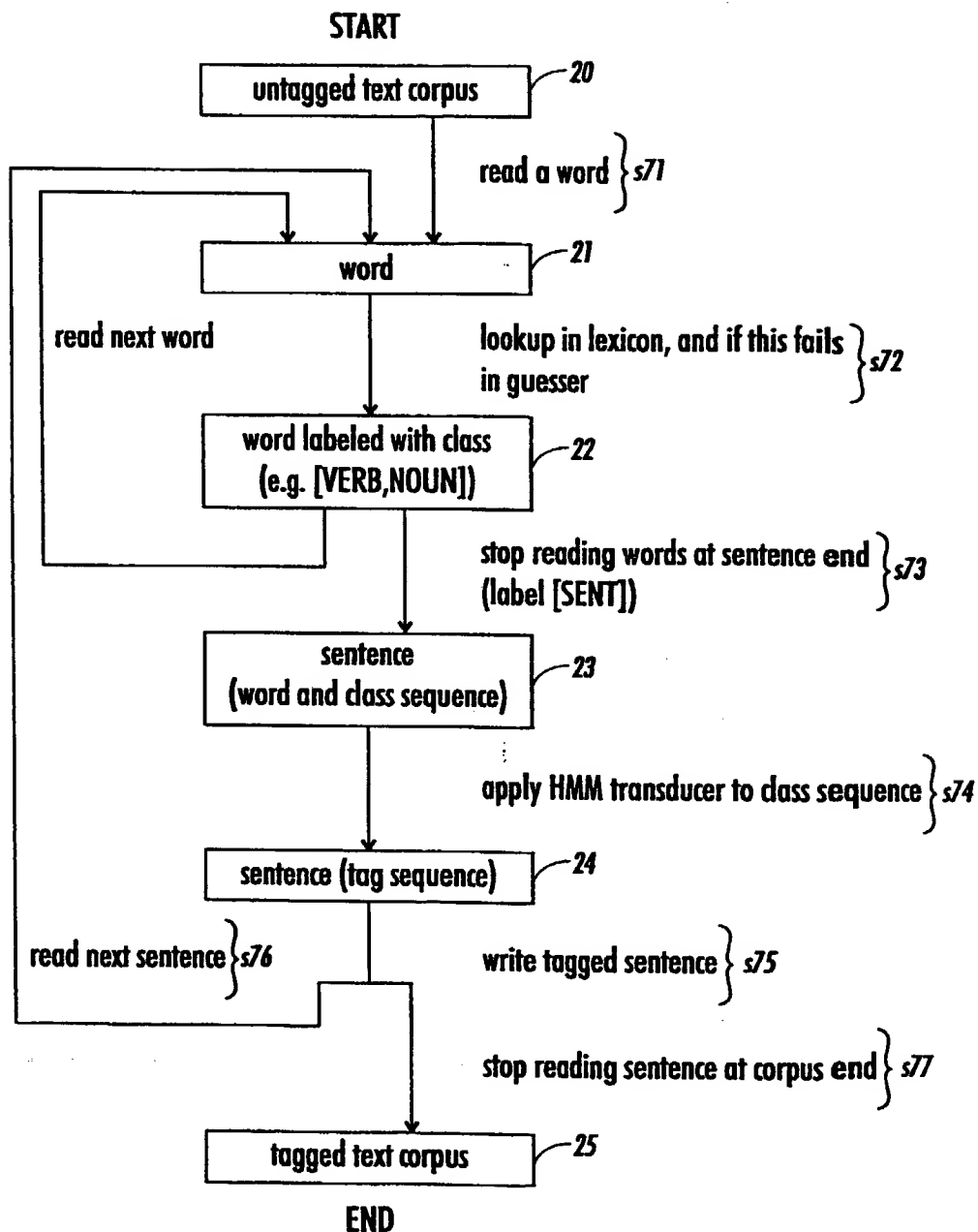


FIG. 11

# INTERNATIONAL SEARCH REPORT

Int l Application No

PCT/EP 98/04153

## A. CLASSIFICATION OF SUBJECT MATTER

IPC 6 G06F17/27

According to International Patent Classification (IPC) or to both national classification and IPC

## B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 6 G06F

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

## C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
P, X	<p>A. KEMPE: "Finite State Transducers Approximating Hidden Markov Models." PROCEEDINGS OF THE 35TH ANNUAL MEETING OF THE ASSOCIATION FOR COMPUTATIONAL LINGUISTICS, 7 - 12 July 1997, pages 460-467, XP002085043 Madrid, Spain see the whole document</p> <p style="text-align: center;">-/--</p>	<p>1-8, 10-12</p>



Further documents are listed in the continuation of box C.



Patent family members are listed in annex.

\* Special categories of cited documents:

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"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

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"3" document member of the same patent family

Date of the actual completion of the international search

19 November 1998

Date of mailing of the international search report

04/12/1998

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Pedersen, N

# INTERNATIONAL SEARCH REPORT

Int. Application No.

PCT/EP 98/04153

## C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
P,X	<p>A. KEMPE: "Look-Back and Look-Ahead in the Conversion of Hidden Markov Models into finite state transducers."            PROCEEDINGS OF THE JOINT CONFERENCE ON NEW METHODS IN LANGUAGE PROCESSING AND COMPUTATIONAL NATURAL LANGUAGE LEARNING,            15 - 17 January 1998, pages 29-37,            XP002085044            Sydney,            (http://www.xrce.xerox.com/publis/mltt/mlttart.html)            Available on the internet 10th October 1998            see the whole document</p>	9-12
P,X	<p>CHARNIAK E: "Statistical techniques for natural language parsing"            AI MAGAZINE, WINTER 1997, AMERICAN ASSOC. ARTIFICIAL INTELLIGENCE, USA,            vol. 18, no. 4, pages 33-44, XP002085045            ISSN 0738-4602            see page 34, column 1, line 3 - page 35, column 1, line 13            see page 39, column 2, line 5 - page 40, column 1, line 1            see figure 4</p>	1-4, 10-12
X	<p>PEREIRA F ET AL: "WEIGHTED RATIONAL TRANSDUCTION AND THEIR APPLICATION TO HUMAN LANGUAGE PROCESSING"            HUMAN LANGUAGE TECHNOLOGY. PROCEEDINGS OF A WORKSHOP, 1 January 1994, pages 262-267,            XP000571116</p>	1-3, 10-12
Y	<p>see page 262, column 1, line 1 - page 263, column 1, line 34</p>	5-9
Y	<p>TAPANAINEN P ET AL: "Syntactic Analysis of Natural Language using Linguistic Rules and Corpus-Based Patterns"            PROCEEDINGS OF THE FIFTEENTH INTERNATIONAL CONFERENCE ON COMPUTATIONAL LINGUISTICS (COLING94),            vol. 1, 1994, pages 629-634, XP002085046            Kyoto, Japan            see page 629, column 1, line 18 - column 1, line 45            see page 629, column 2, line 20 - line 35            see page 631, column 2, line 19 - line 59</p>	5-9
X	<p>US 5 610 812 A (SCHABES YVES ET AL)            11 March 1997            see column 6, line 63 - column 12, line 37            see figures 2-7</p>	1,4, 10-12

-/--

# INTERNATIONAL SEARCH REPORT

In International Application No

PCT/EP 98/04153

## C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	<p>ROCHE E ET AL: "Deterministic part-of-speech tagging with finite-state transducers"</p> <p>COMPUTATIONAL LINGUISTICS, JUNE 1995, USA, vol. 21, no. 2, pages 227-253, XP002085047</p> <p>ISSN 0891-2017</p> <p>see page 231, line 6 - page 234, line 12</p> <p>see page 236, line 16 - line 26</p> <p>see page 242, line 1 - page 243, line 24</p>	1,4, 10-12
A	<p>KAPLAN R M ET AL: "REGULAR MODELS OF PHONOLOGICAL RULE SYSTEMS"</p> <p>COMPUTATIONAL LINGUISTICS, vol. 20, no. 3, 1 September 1994, pages 331-378, XP000569407</p> <p>see page 333, line 46 - page 338, line 36</p>	1-12
A	<p>RABINER L R: "A tutorial on hidden Markov models and selected applications in speech recognition"</p> <p>PROCEEDINGS OF THE IEEE, FEB. 1989, USA, vol. 77, no. 2, pages 257-286, XP002085048</p> <p>ISSN 0018-9219</p> <p>see page 258, column 2, line 3 - page 259, column 1, line 26</p>	1-12

# INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No

PCT/EP 98/04153

Patent document  
cited in search report

Publication  
date

Patent family  
member(s)

Publication  
date

US 5610812 A

11-03-1997

JP 8055122 A

27-02-1996